

Your Global Automation Partner



RI360P0-...-IOLX2-.../3GD Encoders with IO-Link Interface

Instructions for Use

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1 About these instructions

These instructions for use describe the structure, functions and the use of the product and will help you to operate the product as intended. Read these instructions carefully before using the product. This is to avoid possible damage to persons, property or the device. Retain the instructions for future use during the service life of the product. If the product is passed on, pass on these instructions as well.

1.1 Target groups

These instructions are aimed at qualified personnel with knowledge of explosion protection (e.g. EN 60079-14 etc.) and must be carefully read by anyone mounting, commissioning, operating, maintaining, dismantling or disposing of the device.

1.2 Explanation of symbols used

The following symbols are used in these instructions:



DANGER

DANGER indicates a dangerous situation with high risk of death or severe injury if not avoided.



WARNING

WARNING indicates a dangerous situation with medium risk of death or severe injury if not avoided.



CAUTION

CAUTION indicates a dangerous situation of medium risk which may result in minor or moderate injury if not avoided.



NOTICE

NOTICE indicates a situation which may lead to property damage if not avoided.



NOTE

NOTE indicates tips, recommendations and useful information on specific actions and facts. The notes simplify your work and help you to avoid additional work.



CALL TO ACTION

This symbol denotes actions that the user must carry out.



RESULTS OF ACTION

This symbol denotes relevant results of actions.

1.3 Other documents

Besides this document, the following material can be found on the Internet at www.turck.com:

- Data sheet
- Quick Start Guide
- IO-Link parameters manual
- Commissioning manual IO-Link devices

1.4 Feedback about these instructions

We make every effort to ensure that these instructions are as informative and as clear as possible. If you have any suggestions for improving the design or if some information is missing in the document, please send your suggestions to techdoc@turck.com.

2 Notes on the product

2.1 Product identification

These instructions apply to the following encoder:

- RI360P0-QR24M0-IOLX2-H1141/3GD

2.2 Scope of delivery

The scope of delivery includes:

- Encoder – Sensor
- Mounting aid MT-QR24
- Quick Start Guide

2.3 Turck service

Turck supports you with your projects, from initial analysis to the commissioning of your application. The Turck product database under www.turck.com contains software tools for programming, configuration or commissioning, data sheets and CAD files in numerous export formats.

The contact details of Turck subsidiaries worldwide can be found on p. [► 35].

3 For your safety

The product is designed according to state-of-the-art technology. However, residual risks still exist. Observe the following warnings and safety notices to prevent damage to persons and property. Turck accepts no liability for damage caused by failure to observe these warning and safety notices.

3.1 Intended use

The rotary encoders with an IO-Link interface are used for measuring speeds and angle movements. To do this the devices detect mechanical rotary movements and convert them into a digital IO-Link telegram. The devices can be operated and parameterized via an IO-Link interface with IO-Link masters compliant with specification 1.1. Process and diagnostics data can be exchanged with the higher controller level during operation via IO-Link.

The device is suitable for operation in zone 2 and zone 22.

The devices may only be used as described in these instructions. Any other use is not in accordance with the intended use. Turck accepts no liability for any resulting damage.

3.2 Obvious misuse

- The devices are not safety components and must not be used for personal or property protection.
- Any use that exceeds the maximum permissible mechanical speed (see technical data) is deemed to be not in accordance with the intended purpose.

3.3 General safety notes

- The device may only be assembled, installed, operated, parameterized and maintained by professionally-trained personnel.
- If safe operation can no longer be guaranteed: Shut down the device and lock out to prevent accidental startups.
- The device may only be used in accordance with applicable national and international regulations, standards and laws.
- The device meets the EMC requirements for industrial areas. When used in residential areas, take measures to avoid radio interference.

3.4 Notes on Ex protection

- When operating the device in a hazardous area, the user must have a working knowledge of explosion protection (IEC/EN 60079-14, etc.).
- Observe national and international regulations for explosion protection.
- Only use the device within the permitted operating and ambient conditions (see certification data and Ex approval requirements for use in Ex area).

3.5 Requirements for Ex approval for operation in zone 2 and 22

- Connect the device using a separately certified M12 plug connection. The plug connection must meet the requirements of IEC/EN 61076-2-101.
- Secure the male connector with the supplied SC-PM12/3GD safety clip.
- Permanently affix a label close to the connector with the following warning: NICHT UNTER SPANNUNG TRENNEN/DO NOT SEPARATE WHEN ENERGIZED
- Only use devices with a protecting ring or impact protection.

4 Product description

The inductive encoders of the RI360P...-QR24 series measure speeds and angle movements up to 360°. The sensor and positioning element of encoders are fully potted and designed as two separate fully sealed units with protection type IP69K that work together without contact. The encoder sensor can be connected to shafts with a diameter of up to 20 mm using the reducing bushings and mounting elements which are available as an option. A mounting element for mounting on large rotatable machine parts is also included in the range.

The QR24 encoders with an IO-Link interface can be connected via a 3-wire connection cable with a 4-pin standard male connector. The devices can be operated and set via IO-Link.

4.1 Device overview

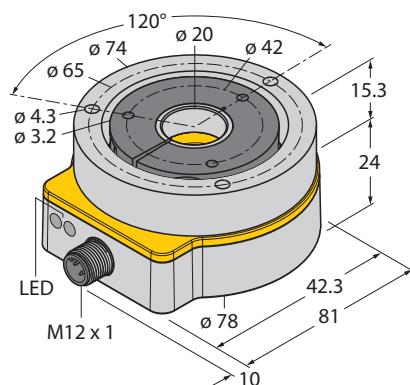


fig. 1: QR24 encoder with sensor, P1 positioning element (optional) and protecting ring (optional)

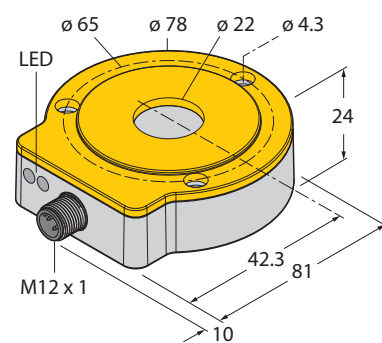


fig. 2: Encoder — sensor (front)

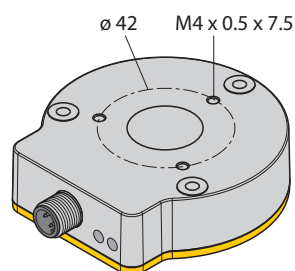


fig. 3: Encoder — sensor (rear)

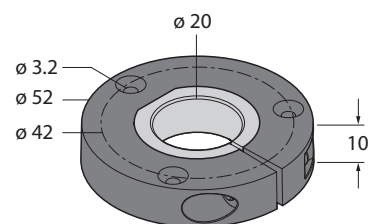


fig. 4: Encoder — positioning element P1

4.1.1 Indication elements

The devices are provided with a green Power supply LED and a yellow Status LED.

4.2 Properties and features

- Operation and setting via IO-Link
- Single-turn, 16-bit resolution
- Process value in 32-bit IO-Link telegram
- 3 error bits
- 13 multiturn bits
- 16 single-turn bits
- Connection via 4-pin M12 × 1 male connector

4.3 Operating principle

The QR24 encoders have contactless operation based on the inductive resonant circuit measuring principle. This measuring principle makes it possible to design a fully encapsulated sensor housing without seals, which is separated from the positioning element. Magnetic fields cannot disturb the measuring process since the positioning element is not based on a magnet but on an inductive coil system, through which the sensor and the positioning element (resonator) can form an oscillation circuit. The inductive measuring principle of the QR24 encoder is absolute.

4.4 Functions and operating modes

The devices can be operated in IO-Link mode. The devices must be connected to an IO-Link master for operation in IO-Link mode. Different device functions can be configured via the IO-Link interface.

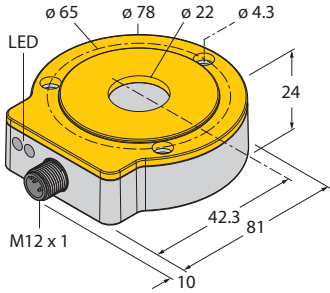
4.4.1 IO-Link mode

IO-Link mode provides bidirectional IO-Link communication between an IO-Link master and the sensors. For this the devices are integrated in the controller level via an IO-Link master. The switching signals are processed via the process data of the IO-Link interface. Besides the switching information, diagnostics and identification messages can be queried via IO-Link. The following device parameters can be adapted to the particular application via IO-Link:

- Device access protection
- Rotation direction
- Zero setting
- Multiturn reset
- Reset settings

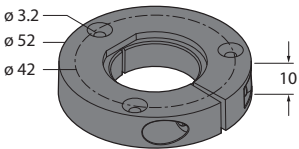
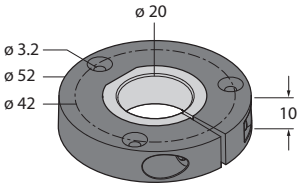
4.5 Encoders — components and accessories

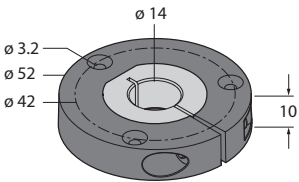
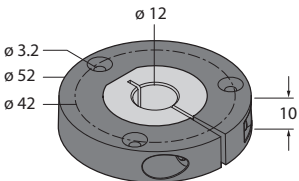
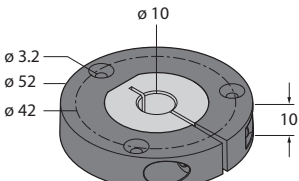
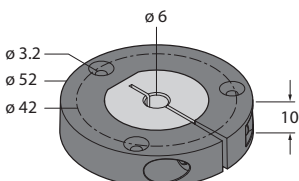
4.5.1 Encoder — QR24/3GD sensor

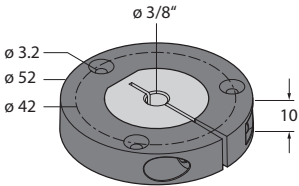
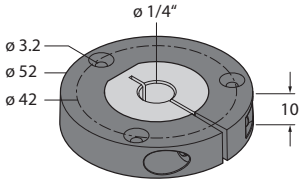
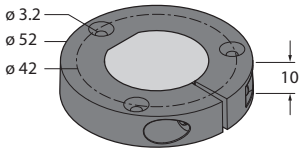
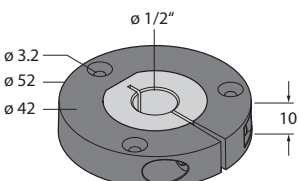
| Dimension drawing | Type | Description |
|---|---------------------------|--|
|  | RI360P...- QR24.../3GD | Encoder – sensor, QR24 design, die cast zinc housing (without positioning element) |

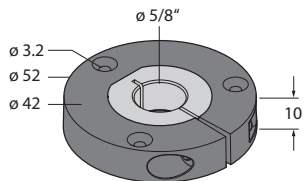
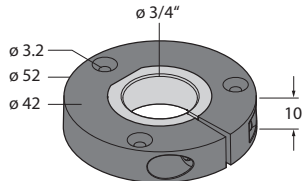
4.5.2 Encoder — QR24 positioning element

The positioning elements are connected with the moving part of the machine (shaft) but move freely (without any mechanical connection to the sensor) over the active face of the sensor. Different reducing bushings are available to adapt the positioning element to the particular shaft diameter.

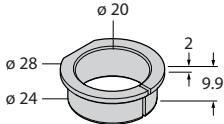
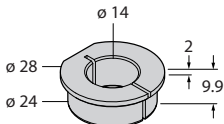
| Dimension drawing | Type | Description |
|---|------------|---|
|  | PE1-QR24 | Positioning element without reducing bushing |
|  | P1-RI-QR24 | Positioning element with aluminum reducing bushing to connect to Ø 20 mm shafts |

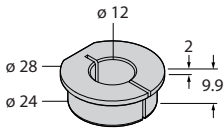
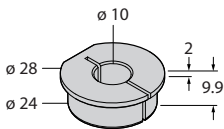
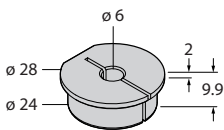
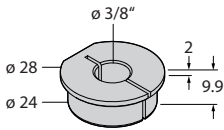
| Dimension drawing | Type | Description |
|---|------------|---|
|  | P2-RI-QR24 | Positioning element with aluminum reducing bushing to connect to Ø 14 mm shafts |
|  | P3-RI-QR24 | Positioning element with aluminum reducing bushing to connect to Ø 12 mm shafts |
|  | P4-RI-QR24 | Positioning element with aluminum reducing bushing to connect to Ø 10 mm shafts |
|  | P5-RI-QR24 | Positioning element with aluminum reducing bushing to connect to Ø 6 mm shafts |

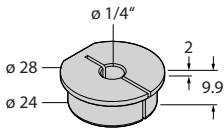

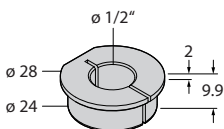
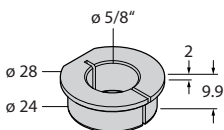
| Dimension drawing | Type | Description |
|---|------------|---|
|  | P6-RI-QR24 | Positioning element with aluminum reducing bushing to connect to Ø 3/8" shafts |
|  | P7-RI-QR24 | Positioning element with aluminum reducing bushing to connect to Ø 1/4" shafts |
|  | P8-RI-QR24 | Positioning element with aluminum blanking plug, e.g. for mounting on large rotatable machine parts |
|  | P9-RI-QR24 | Positioning element with aluminum reducing bushing to connect to Ø 1/2" shafts |

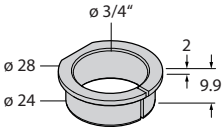
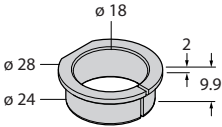
| Dimension drawing | Type | Description |
|---|-------------|--|
|  | P10-RI-QR24 | Positioning element with aluminum reducing bushing to connect to Ø 5/8" shafts |
|  | P11-RI-QR24 | Positioning element with aluminum reducing bushing to connect to Ø 3/4" shafts |

4.5.3 Encoder — QR24 reducing bushings for PE1-QR24 positioning elements

| Dimension drawing | Type | Description |
|---|----------|--|
|  | RA1-QR24 | Aluminum reducing bushing to connect to Ø 20 mm shafts |
|  | RA2-QR24 | Aluminum reducing bushing to connect to Ø 14 mm shafts |

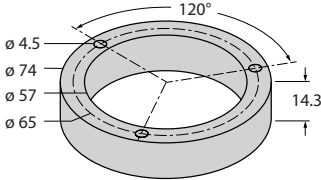
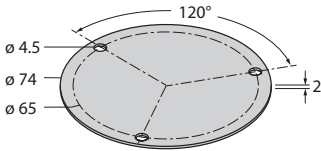
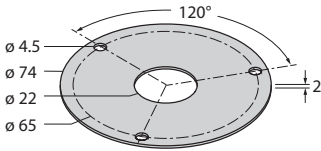
| Dimension drawing | Type | Description |
|---|----------|--|
|  | RA3-QR24 | Aluminum reducing bushing to connect to Ø 12 mm shafts |
|  | RA4-QR24 | Aluminum reducing bushing to connect to Ø 10 mm shafts |
|  | RA5-QR24 | Aluminum reducing bushing to connect to Ø 6 mm shafts |
|  | RA6-QR24 | Aluminum reducing bushing to connect to Ø 3/8" shafts |

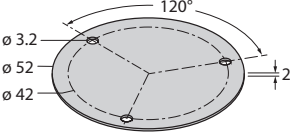
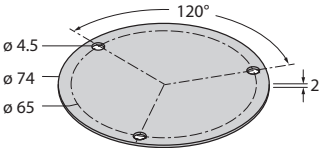
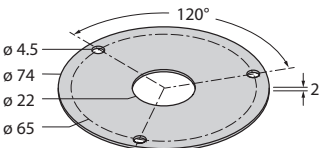
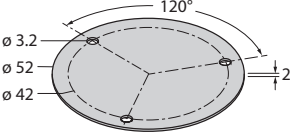
| Dimension drawing | Type | Description |
|---|-----------|--|
|  | RA7-QR24 | Aluminum reducing bushing to connect to Ø 1/4" shafts |
|  | RA8-QR24 | Aluminum reducing bushing (e.g. for mounting the positioning element on large rotatable machine parts) |
|  | RA9-QR24 | Aluminum reducing bushing to connect to Ø 1/2" shafts |
|  | RA10-QR24 | Aluminum reducing bushing to connect to Ø 5/8" shafts |

| Dimension drawing | Type | Description |
|---|-----------|--|
|  | RA11-QR24 | Aluminum reducing bushing to connect to Ø 3/4" shafts |
|  | RA12-QR24 | Aluminum reducing bushing to connect to Ø 18 mm shafts |

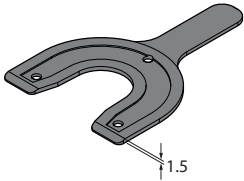
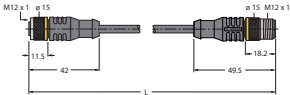
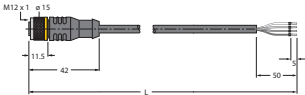
4.5.4 Encoders — protecting rings and mounting sets for QR24 device types

Different mounting sets are required for different mounting types (see section “Mounting”). Each mounting set contains an aluminum protecting ring and an aluminum shielding plate. The shield plates enable the quality of the signal between the positioning element and the sensor to be increased depending on mounting type and application. The protecting rings are also available individually in aluminum and plastic.

| Dimension drawing | Type | Description |
|---|---------|---|
|  | M1-QR24 | Aluminum protecting ring |
|  | M2-QR24 | Mounting set (for front mounting of the sensor on shafts up to Ø 20 mm): M1-QR24 aluminum protecting ring + SP1-QR24 aluminum shield plate: Ø 74 mm |
|  | M3-QR24 | Mounting set (for front mounting of the sensor on shafts up to Ø 20 mm): M1-QR24 aluminum protecting ring + SP2-QR24 aluminum shield plate: Ø 74 mm, with Ø 22 mm hole for shaft feedthrough |

| Dimension drawing | Type | Description |
|---|----------|---|
|  | M4-QR24 | Mounting set (for mounting the positioning element on large rotatable machine parts): M1-QR24 aluminum protecting ring + SP3-QR24 aluminum shield plate: Ø 52 mm |
|  | SP1-QR24 | Aluminum shield plate: Ø 74 mm for rear mounting of the sensor on shafts up to Ø 20 mm |
|  | SP2-QR24 | Aluminum shield plate: Ø 74 mm, with Ø 22 mm hole for shaft feedthrough for front mounting of the sensor on shafts up to Ø 20 mm |
|  | SP3-QR24 | Aluminum shield plate: Ø 52 mm for mounting the positioning element on large rotatable machine parts |

4.5.5 Encoders — general accessories

| Dimension drawing | Type | Description |
|---|-----------------------|---|
|  | MT-QR24 | Mounting aid for optimum alignment of the positioning element (supplied) |
|  | RKC4.4T-2-RSC4.4T/TXL | Connection cable, M12 female connector, straight 4-pin, M12 male connector, straight 4-pin, cable length: 2 m, jacket material: PUR, black; cULus approval; other cable lengths and qualities available, see www.turck.com |
|  | RKC4.4T-2/TXL | Connection cable, M12 female connector, straight 4-pin, cable length: 2 m, jacket material: PVC, black; cULus approval; other cable lengths and qualities available, see www.turck.com |

5 Installing

The optionally available adapter sleeves and mounting elements enable the front or rear of the encoder sensors to be fitted to the shafts with a diameter of up to 20 mm. With large rotatable machine parts, the positioning element is screwed directly onto the machine part and not fitted on the shaft.



WARNING

Improper fixing

Possible fatal injury from fast moving parts!

- ▶ Observe mounting instructions in all cases.
- ▶ Check the secure seating of the positioning element, tightening torque:
 $M = 0.6 \dots 0.8 \text{ Nm}$.



NOTICE

Insufficient clearance from metal surrounding the positioning element

Loss of functionality due to weakening of resonant circuit

- ▶ Ensure sufficient clearance between the surrounding area and positioning element.
- ▶ Carry out a function test prior to commissioning.



NOTE

The positioning element must be located in the middle of the measuring range of the sensor before the power supply is applied.

5.1 Front mounting — shaft diameters up to 20 mm

1. Optional: Use shield plate.
2. Position the mounting aid for optimum alignment of the positioning element.

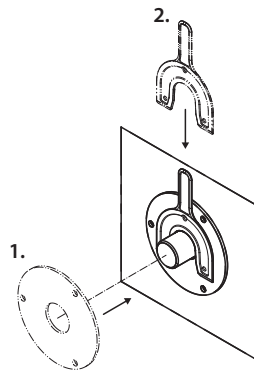


fig. 5: Inserting the shield plate

3. Push the positioning element – with the front (active face) to the shaft – onto the shaft.
4. Fasten clamp fitting of the positioning element with hexagon spanner.

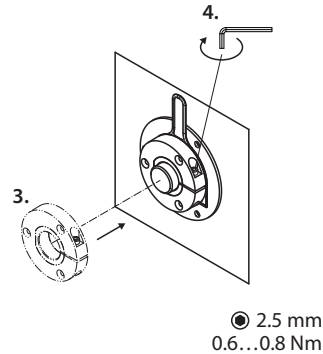


fig. 6: Fastening the positioning element

5. Remove mounting aid.
6. Place the encoder sensor including the protecting ring with the front to the shaft over the positioning element and align to the required position of the zero point. (factory setting for 0°: yellow arrow on the positioning element pointing to the black mark on the sensor, see figure “Zero point default value”.)

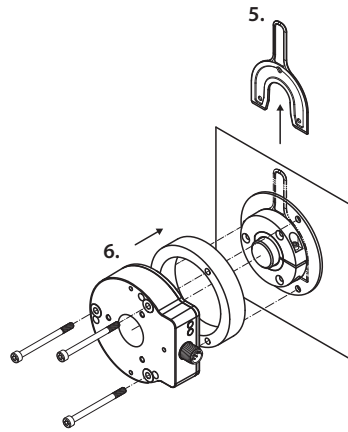


fig. 7: Fastening the encoder

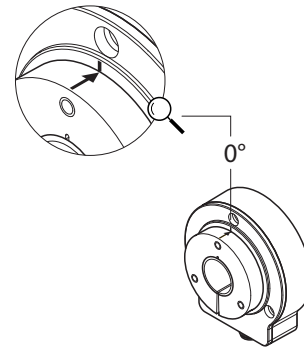


fig. 8: Zero point default value

- Fasten the encoder with three screws in order to produce a closed and protected unit.

5.2 Rear mounting — shaft diameters up to 20 mm

There are different options for the first mounting step, depending on the environmental conditions.

1. Option 1: Push the encoder with the rear to the shaft onto the shaft and fasten with the three screws onto a fixing plate with a threaded hole.

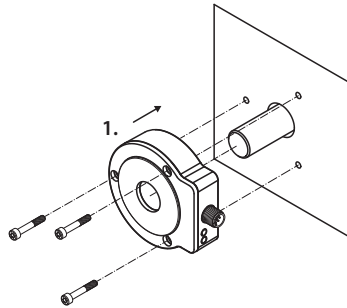


fig. 9: Mounting the encoder on a fixing plate

1. Option 2: Push the encoder with the rear to the shaft onto the shaft and fasten with three screws in the encoder.

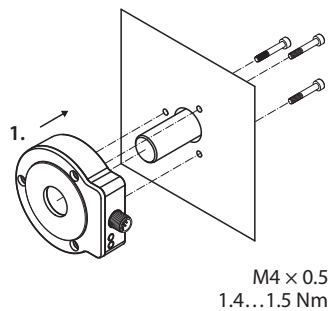


fig. 10: Fastening screws in the encoder

2. Position the mounting aid for optimum alignment of the positioning element.
3. Push the positioning element onto the shaft and align to the required position of the zero point. (factory setting for 0°: yellow arrow on the positioning element pointing to the black mark on the sensor, see figure "Zero point default value".)
4. Fasten clamp fitting of the positioning element with hexagon spanner.

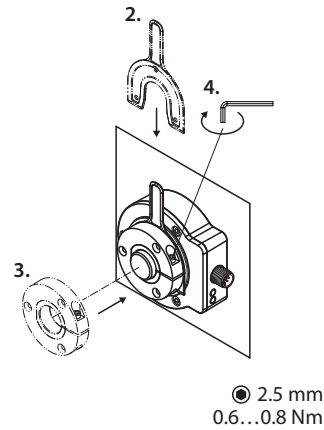


fig. 11: Fastening the positioning element

5. Remove mounting aid.

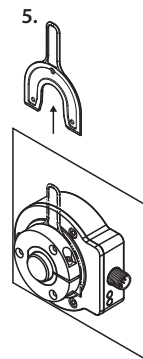


fig. 12: Removing the mounting aid

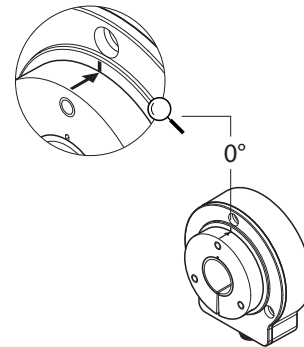


fig. 13: Zero point default value

- Optional: Use protecting ring and shield plate.

4. Fasten the positioning element with three M3 countersunk screws (recommended: stainless steel screws).

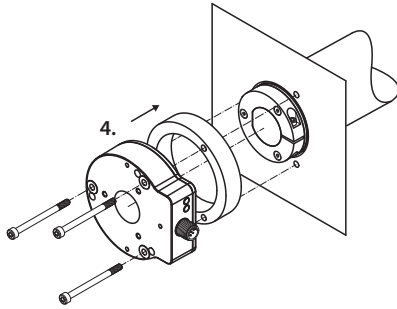


fig. 16: Fastening the positioning element

- Depending on the application, mount the encoder and align to the required position of the zero point. (factory setting for 0°: yellow arrow on the positioning element pointing to the black mark on the sensor, see figure "Zero point default value".)

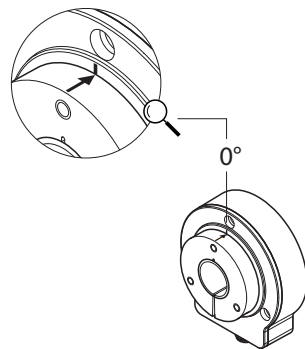


fig. 17: Zero point default value

6 Connection



DANGER

Explosive atmosphere

Risk of explosion through spark ignition

Use in zone 2 or zone 22:

- ▶ Only connect the device if there is no potentially explosive atmosphere present or when it is in a de-energized state.
- ▶ Provide the connector on the device with an additional safety clip.

The encoder is provided with a 4-pin M12 x 1 male connector with an IO-Link interface.

- ▶ Connect the female connector of the connection cable to the M12 male connector of the device.
- ▶ Connect the open end of the connection cable to the IO-Link master, fieldbus device or controller with suitable inputs as shown in the wiring diagram and the terminal layout of the relevant connected device.
- ▶ Affix a label close to the connector with the following warning: "NICHT UNTER SPANNUNG TRENNEN/DO NOT SEPARATE WHEN ENERGIZED".

6.1 Wiring diagram

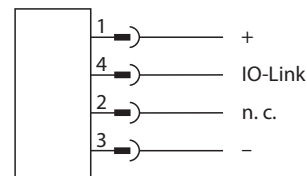
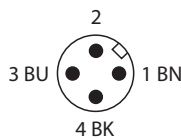


fig. 18: M12 male connector — pin assignment fig. 19: M12 male connector — wiring diagram

7 Commissioning

The device is operational automatically once the connection is made and the power supply is switched on. If the device is connected to an IO-Link master, IO-Link communication starts automatically. For this the IO-Link master sends a wakeup request to the device. The transfer speed depends on the transfer rate set in the IO-Link master.

7.1 Setting IO-Link mode

- ▶ Set the cycle time on the IO-Link master.
- ⇒ The device is operational.

8 Operation

The encoder supplies at the output the IO-Link process data corresponding proportionally to the position of the positioning element. The IO-Link process data contains the following information:

- Current angle information (single-turn data)
- Number of revolutions of the positioning element (Semi-multiturn data):
The multiturn process data is calculated internally from the number of single-turn zero crossings. The sensor does not detect any revolutions when de-energized. If the encoder is moved during a power failure, this is indicated on restart by a status bit. The status bit makes it possible to evaluate the correctness of the multiturn process data.

8.1 Maximum speed



WARNING

Improper fixing

Possible fatal injury from fast moving parts!

- ▶ Do not exceed the maximum speed of 800 rpm.
- ▶ Observe mounting instructions in all cases.
- ▶ Check the secure seating of the positioning element, tightening torque:
 $M = 0.6 \dots 0.8 \text{ Nm}$.

8.2 LED display

In normal operation the LEDs have the following indication functions:

| Color/state | Meaning |
|-----------------|---|
| Green flashing | Sensor power supply correct. |
| Yellow off | Positioning element is within the measuring range. |
| Yellow | Positioning element is within the measuring range, reduced signal quality (e.g. gap too large). |
| Yellow flashing | Positioning element is not within the measuring range. |

9 Setting

The encoder can be set via the IO-Link interface.

9.1 Setting via IO-Link

The devices can be parameterized via the IO-Link communication interface within the limits of their technical specifications. For further information on IO-Link see the IO-Link commissioning manual (D900634).

9.1.1 IO-Link parameters

Different parameters can be set for the particular application via the IO-Link interface. Further information on the IO-Link parameters can be obtained from the IO-Link parameter manual or the **IODDfinder**.

The default values are shown in **bold** type.

| Parameter | Parameter value |
|--|-------------------|
| Block device access | On |
| (switch off parameter server function) | Off |
| Rotation direction | Clockwise |
| | Counter clockwise |
| Set zero point and reset multiturn | |
| Multiturn reset | |
| Reset to factory setting | |
| Application-specific marking | |

9.1.2 IO-Link process data

| Process data (bit) | | | | |
|-------------------------|-----------------------|-----------------|-------------------|----------|
| 0 | 1 | 2 | 3...15 | 16...31 |
| Resonance coupling weak | No resonance coupling | Multiturn fault | Multiturn counter | Position |

10 Troubleshooting

The strength of the resonance coupling is indicated by an LED. Any faults are indicated via the LEDs.

If the device does not function as expected, first check whether ambient interference is present. If there is no ambient interference present, check the connections of the device for faults.

If there are no faults, there is a device malfunction. In this case, decommission the device and replace it with a new device of the same type.

11 Maintenance

Ensure that the plug connections and cables are always in good condition.

The devices are maintenance-free, clean dry if required.

12 Decommissioning

- ▶ Disconnect the connection cable from the power supply and/or processing units.
- ▶ Disconnect the connection cable from the device.
- ▶ Undo the connections of the device or if necessary the mounting aid for the mounting area.
- ▶ If present: undo the connection between the device and the mounting aid.

13 Disposal





The devices must be disposed of correctly and must not be included in general household garbage.

14 Technical data

| Technical data | |
|---|---|
| Max. speed | 800 rpm |
| Starting torque, shaft load (radial/axial) | Not applicable with contactless measuring principle |
| Measuring range | 0...360° |
| Nominal distance | 1.5 mm |
| Repetition accuracy | ≤ 0.01 % of full scale |
| Linearity deviation | ≤ 0.05 % of full scale |
| Temperature drift | ≤ ± 0.003 %/K |
| Output type | Absolute semi multiturn |
| Single turn resolution | 16-bit/65536 increments per revolution |
| Multiturn resolution | 13-bit/8192 revolutions |
| Number of diagnostic bits | 3-bit |
| Electrical data | |
| Operating voltage | 15...30 VDC |
| Ripple | ≤ 10 % U _{ss} |
| Insulation test voltage | ≤ 0.5 kV |
| Wire break / reverse polarity protection | Yes (voltage supply) |
| Output function | 4-pin, IO-Link |
| Sampling rate | 1000 Hz |
| Current consumption | < 50 mA |
| IO-Link specification | Specified according to version 1.1 |
| Parameterization | FDT/DTM |
| Process data width | 32-bit |
| Mechanical data | |
| Design | QR24 |
| Dimensions | 81 × 78 × 24 mm |
| Flange type | Flange without fixing element |
| Shaft type | Hollow shaft |
| Housing material | Metal/plastic, ZnAlCu1/PBT-GF30-V0 |
| Connection | Male connector, M12 x 1 |
| Ambient conditions | |
| Ambient temperature | -25...+85 °C, as per UL approval up to 70 °C |
| Vibration resistance | 55 Hz (1 mm) |
| Vibration resistance (EN 60068-2-6) | 20 g, 10...3000 Hz, 50 cycles, 3 axes |
| Shock resistance (EN 60068-2-27) | 100 g, 11 ms ½ sine, 3 × each, 3 axes |
| Continuous shock resistance (EN 60068-2-29) | 40 g, 6 ms ½ sine, 4000 × each, 3 axes |
| Degree of protection | IP68/IP69K |
| MTTF | 138 years acc. to SN 29500 (Ed. 99) 40 °C |
| Operating voltage indication | LED green |
| Status display | LED yellow |

15 Appendix

15.1 Approvals and markings

| Approvals | |
|---|-----------------------------|
| TURCK Ex-18004H X | ⒺⅡ 3 G Ex ec IIA T4 Gc |
|  | ⒺⅡ 3 D Ex tc IIIC T100°C Dc |
| 编码器 | Ex ec IIA T4 Gc |
|  | Ex tc IIIC T100°C Dc |

Ambient temperature T_{amb}: -25...+85 °C

16 Turck subsidiaries — contact information

| | |
|-----------------------|---|
| Germany | Hans Turck GmbH & Co. KG Witzlebenstraße 7, 45472 Mülheim an der Ruhr www.turck.de |
| Australia | Turck Australia Pty Ltd Building 4, 19-25 Duerdin Street, Notting Hill, 3168 Victoria www.turck.com.au |
| Austria | Turck GmbH Graumannsgasse 7/A5-1, A-1150 Wien www.turck.at |
| Belgium | TURCK MULTIPROX Lion d'Orweg 12, B-9300 Aalst www.multiprox.be |
| Brazil | Turck do Brasil Automação Ltda. Rua Anjo Custódio Nr. 42, Jardim Anália Franco, CEP 03358-040 São Paulo www.turck.com.br |
| Canada | Turck Canada Inc. 140 Duffield Drive, CDN-Markham, Ontario L6G 1B5 www.turck.ca |
| China | Turck (Tianjin) Sensor Co. Ltd. 18,4th Xinghuazhi Road, Xiqing Economic Development Area, 300381 Tianjin www.turck.com.cn |
| Czech Republic | TURCK s.r.o. Na Brně 2065, CZ-500 06 Hradec Králové www.turck.cz |
| France | TURCK BANNER S.A.S. 11 rue de Courtalin Bat C, Magny Le Hongre, F-77703 MARNE LA VALLEE Cedex 4 www.turckbanner.fr |
| Great Britain | TURCK BANNER LIMITED Blenheim House, Hurricane Way, GB-SS11 8YT Wickford, Essex www.turckbanner.co.uk |
| Hungary | TURCK Hungary kft. Árpád fejedelem útja 26-28., Óbuda Gate, 2. em., H-1023 Budapest www.turck.hu |
| India | TURCK India Automation Pvt. Ltd. 401-403 Aurum Avenue, Survey. No 109 /4, Near Cummins Complex, Baner-Balewadi Link Rd., 411045 Pune - Maharashtra www.turck.co.in |
| Italy | TURCK BANNER S.R.L. Via San Domenico 5, IT-20008 Bareggio (MI) www.turckbanner.it |

| | |
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| Japan | TURCK Japan Corporation ISM Akihabara 1F, 1-24-2, Taito, Taito-ku, 110-0016 Tokyo www.turck.jp |
| Korea | Turck Korea Co, Ltd. B-509 Gwangmyeong Technopark, 60 Haan-ro, Gwangmyeong-si, 14322 Gyeonggi-Do www.turck.kr |
| Malaysia | Turck Banner Malaysia Sdn Bhd Unit A-23A-08, Tower A, Pinnacle Petaling Jaya, Jalan Utara C, 46200 Petaling Jaya Selangor www.turckbanner.my |
| Mexico | Turck Comercial, S. de RL de CV Blvd. Campestre No. 100, Parque Industrial SERVER, C.P. 25350 Arteaga, Coahuila www.turck.com.mx |
| Netherlands | Turck B. V. Ruiterlaan 7, NL-8019 BN Zwolle www.turck.nl |
| Poland | TURCK sp.z.o.o. Wroclawska 115, PL-45-836 Opole www.turck.pl |
| Romania | Turck Automation Romania SRL Str. Siriului nr. 6-8, Sector 1, RO-014354 Bucuresti www.turck.ro |
| Russian Federation | TURCK RUS OOO 2-nd Pryadilnaya Street, 1, 105037 Moscow www.turck.ru |
| Sweden | Turck Sweden Office Fabriksstråket 9, 433 76 Jonsered www.turck.se |
| Singapore | TURCK BANNER Singapore Pte. Ltd. 25 International Business Park, #04-75/77 (West Wing) German Centre, 609916 Singapore www.turckbanner.sg |
| South Africa | Turck Banner (Pty) Ltd Boeing Road East, Bedfordview, ZA-2007 Johannesburg www.turckbanner.co.za |
| Turkey | Turck Otomasyon Ticaret Limited Sirketi Inönü mah. Kayisdagi c., Yesil Konak Evleri No: 178, A Blok D:4, 34755 Kadiköy/ Istanbul www.turck.com.tr |
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